

LMH6618, LMH6619

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LMH6618 Single/LMH6619 Dual 130 MHz, 1.25 mA RRIO Operational Amplifiers

Check for Samples: LMH6618, LMH6619

FEATURES

- $V_S = 5V$, $R_L = 1 \ k\Omega$, $T_A = 25^{\circ}C$ and $A_V = +1$, Unless Otherwise Specified.
- Operating Voltage Range 2.7V to 11V
- Supply Current per Channel 1.25 mA
- Small Signal Bandwidth 130 MHz
- Input Offset Voltage (Limit at 25°C) ±0.75 mV
- Slew Rate 55 V/µs
- Settling Time to 0.1% 90 ns
- Settling Time to 0.01% 120 ns
- SFDR (f = 100 kHz, A_V = +1, V_{OUT} = 2 V_{PP}) 100 dBc
- 0.1 dB Bandwidth ($A_V = +2$) 15 MHz
- Low Voltage Noise 10 nV/√Hz

Industrial Temperature Grade -40°C to +125°C

• Rail-to-Rail Input and Output

APPLICATIONS

- ADC Driver
- DAC Buffer
- Active Filters
- High Speed Sensor Amplifier
- Current Sense Amplifier
- Portable Video
- STB, TV Video Amplifier

DESCRIPTION

The LMH6618 (single, with shutdown) and LMH6619 (dual) are 130 MHz rail-to-rail input and output amplifiers designed for ease of use in a wide range of applications requiring high speed, low supply current, low noise, and the ability to drive complex ADC and video loads. The operating voltage range extends from 2.7V to 11V and the supply current is typically 1.25 mA per channel at 5V. The LMH6618 and LMH6619 are members of the PowerWise[®] family and have an exceptional power-to-performance ratio.

The amplifier's voltage feedback design topology provides balanced inputs and high open loop gain for ease of use and accuracy in applications such as active filter design. Offset voltage is typically 0.1 mV and settling time to 0.01% is 120 ns which combined with an 100 dBc SFDR at 100 kHz makes the part suitable for use as an input buffer for popular 8-bit, 10-bit, 12-bit and 14-bit mega-sample ADCs.

The input common mode range extends 200 mV beyond the supply rails. On a single 5V supply with a ground terminated 150 Ω load the output swings to within 37 mV of the ground rail, while a mid-rail terminated 1 k Ω load will swing to 77 mV of either rail, providing true single supply operation and maximum signal dynamic range on low power rails. The amplifier output will source and sink 35 mA and drive up to 30 pF loads without the need for external compensation.

The LMH6618 has an active low disable pin which reduces the supply current to 72 μ A and is offered in the space saving 6-Pin SOT package. The LMH6619 is offered in the 8-Pin SOIC package. The LMH6618 and LMH6619 are available with a -40°C to +125°C extended industrial temperature grade.

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Typical Application





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ABSOLUTE MAXIMUM RATINGS (1)

ESD Tolerance ⁽²⁾	
Human Body Model	
For input pins only	2000V
For all other pins	2000V
Machine Model	200V
Supply Voltage ($V_S = V^+ - V^-$)	12V
Junction Temperature ⁽³⁾	150°C max

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics.

(2) Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC)Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

(3) The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A)/|\theta_{JA}|$. All numbers apply for packages soldered directly onto a PC Board.

OPERATING RATINGS⁽¹⁾

Supply Voltage ($V_S = V^+ - V^-$)	2.7V to 11V
Ambient Temperature Range ⁽²⁾	-40°C to +125°C
Package Thermal Resistance (θ _{JA})	
6-Pin SOT (DDC0006A)	231°C/W
8-Pin SOIC (D0008A)	160°C/W

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics.

(2) The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$. All numbers apply for packages soldered directly onto a PC Board.



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+3V ELECTRICAL CHARACTERISTICS

Unless otherwise specified, all limits are guaranteed for $T_J = +25^{\circ}C$, $V^+ = 3V$, $V^- = 0V$, $\overline{\text{DISABLE}} = 3V$, $V_{CM} = V_O = V^+/2$, $A_V = +1$ ($R_F = 0\Omega$), otherwise $R_F = 2 \ k\Omega$ for $A_V \neq +1$, $R_L = 1 \ k\Omega \parallel 5 \ pF$. **Boldface** Limits apply at temperature extremes.⁽¹⁾

Symbol	Parameter	Condition		Тур (3)	Max (2)	Units
Frequen	cy Domain Response					
SSBW	-3 dB Bandwidth Small Signal	$A_V = 1$, $R_L = 1$ k Ω , $V_{OUT} = 0.2$ V_{PP}		120		N 41 1
		$A_V = 2, -1, R_L = 1 \text{ k}\Omega, V_{OUT} = 0.2 V_{PP}$		56		WHZ
GBW	Gain Bandwidth (LMH6618)		55	71		MHz
GBW	Gain Bandwidth (LMH6619)		55	63		MHz
LSBW	-3 dB Bandwidth Large Signal	$A_V = 1$, $R_L = 1$ k Ω , $V_{OUT} = 2$ V_{PP}		13		N 41 I
		$A_V = 2, R_L = 150\Omega, V_{OUT} = 2 V_{PP}$		13		IVITIZ
Peak	Peaking	$A_V = 1, C_L = 5 \text{ pF}$		1.5		dB
0.1 dBBW	0.1 dB Bandwidth	A_V = 2, V_{OUT} = 0.5 V_{PP} , R_F = R_G = 825 Ω		15		MHz
DG	Differential Gain			0.1		%
DP	Differential Phase			0.1		deg
Time Do	main Response					
t _r /t _f	Rise & Fall Time	2V Step, $A_V = 1$		36		ns
SR	Slew Rate	2V Step, $A_V = 1$	36	46		V/µs
t _{s_0.1}	0.1% Settling Time	2V Step, A _V = −1		90		
t _{s_0.01}	0.01% Settling Time	2V Step, A _V = −1		120		ns
Noise an	nd Distortion Performance					
SFDR	Spurious Free Dynamic Range	f_{C} = 100 kHz, V_{OUT} = 2 V_{PP} , R_{L} = 1 k Ω		100		
		f_{C} = 1 MHz, V_{OUT} = 2 V_{PP} , R_{L} = 1 k Ω		61		dBc
		$f_C = 5 \text{ MHz}, V_{OUT} = 2 V_{PP}, R_L = 1 \text{ k}\Omega$		47		
e _n	Input Voltage Noise Density	f = 100 kHz		10		nV//√Hz
i _n	Input Current Noise Density	f = 100 kHz		1		pA//√Hz
СТ	Crosstalk (LMH6619)	$f = 5 \text{ MHz}, \text{ V}_{IN} = 2 \text{ V}_{PP}$		80		dB
Input, DO	C Performance					
V _{OS}	Input Offset Voltage	$V_{CM} = 0.5V$ (pnp active) $V_{CM} = 2.5V$ (npn active)		0.1	±0.75 ±1.3	mV
TCV _{OS}	Input Offset Voltage Temperature Drift	(4)		0.8		μV/°C
I _B	Input Bias Current	$V_{CM} = 0.5V$ (pnp active)		-1.4	-2.6	
		$V_{CM} = 2.5V$ (npn active)		+1.0	+1.8	μΑ
I _{OS}	Input Offset Current			0.01	±0.27	μA
C _{IN}	Input Capacitance			1.5		pF
R _{IN}	Input Resistance			8		MΩ
CMVR	Common Mode Voltage Range	DC, CMRR ≥ 65 dB	-0.2		3.2	V
CMRR	Common Mode Rejection Ratio	tio V _{CM} Stepped from -0.1V to 1.4V 7		96		dP
		V_{CM} Stepped from 2.0V to 3.1V	81	107		uD
A _{OL}	Open Loop Voltage Gain	$R_L = 1 \text{ k}\Omega \text{ to } +2.7 \text{V or } +0.3 \text{V}$	85	98		dB
		$R_L = 150\Omega$ to +2.6V or +0.4V	76	82		uD

(1) Boldface limits apply to temperature range of -40°C to 125°C

(2) Limits are 100% production tested at 25°C. Limits over the operating temperature range are guaranteed through correlations using the Statistical Quality Control (SQC) method.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

(4) Voltage average drift is determined by dividing the change in V_{OS} by temperature change.

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+3V ELECTRICAL CHARACTERISTICS (continued)

Unless otherwise specified, all limits are guaranteed for $T_J = +25^{\circ}C$, $V^+ = 3V$, $V^- = 0V$, $\overline{\text{DISABLE}} = 3V$, $V_{CM} = V_O = V^+/2$, $A_V = +1$ ($R_F = 0\Omega$), otherwise $R_F = 2 \ k\Omega$ for $A_V \neq +1$, $R_L = 1 \ k\Omega \parallel 5 \ pF$. **Boldface** Limits apply at temperature extremes.⁽¹⁾

Symbol	Parameter	Condition	Min (2)	Тур (3)	Max (2)	Units	
Output I	DC Characteristics	·				-	
V _{OUT}	Output Voltage Swing High (LMH6618) (Voltage from V ⁺ Supply Rail)	$R_L = 1 \ k\Omega$ to V ⁺ /2		50	56 62		
		$R_L = 150\Omega$ to V ⁺ /2		160	172 198		
Output Voltage Swing Low (LMH6618) (Voltage from V ⁻ Supply Rail)	$R_L = 1 \ k\Omega$ to V ⁺ /2		60	66 74	mV from either rail		
	$R_L = 150\Omega$ to V ⁺ /2		170	184 217			
		$R_L = 150\Omega$ to V ⁻		29	39 43		
	Output Voltage Swing High (LMH6619) (Voltage from V ⁺ Supply Rail)	$R_L = 1 \ k\Omega$ to V ⁺ /2		50	56 62		
		$R_L = 150\Omega$ to V ⁺ /2		160	172 198		
	Output Voltage Swing Low (LMH6619) (Voltage from V [−] Supply Rail)	$R_L = 1 \ k\Omega$ to V ⁺ /2		62	68 76	mV from either rail	
		$R_L = 150\Omega$ to V ⁺ /2		175	189 222		
		$R_L = 150\Omega$ to V ⁻		34	44 48		
I _{OUT}	Linear Output Current	$V_{OUT} = V^{+}/2^{(5)}$	±25	±35		mA	
R _{OUT}	Output Resistance	f = 1 MHz		0.17		Ω	
Enable F	Pin Operation						
	Enable High Voltage Threshold	Enabled	2.0			V	
	Enable Pin High Current	$V_{\overline{\text{DISABLE}}} = 3V$		0.04		μA	
	Enable Low Voltage Threshold	Disabled			1.0	V	
	Enable Pin Low Current	$V_{\overline{\text{DISABLE}}} = 0V$		1		μA	
t _{on}	Turn-On Time			25		ns	
t _{off}	Turn-Off Time			90		ns	
Power S	upply Performance						
PSRR	Power Supply Rejection Ratio	DC, V_{CM} = 0.5V, V_S = 2.7V to 11V	84	104		dB	
I _S	Supply Current (LMH6618)	R _L = ∞		1.2	1.5 1.7		
	Supply Current (LMH6619) (per channel)	R _L = ∞		1.2	1.5 1.75	— mA	
I _{SD}	Disable Shutdown Current	DISABLE = 0V		59	85	μA	

(5) Do not short circuit the output. Continuous source or sink currents larger than the I_{OUT} typical are not recommended as it may damage the part.



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+5V ELECTRICAL CHARACTERISTICS

Unless otherwise specified, all limits are guaranteed for $T_J = +25^{\circ}C$, $V^+ = 5V$, $V^- = 0V$, $\overline{\text{DISABLE}} = 5V$, $V_{CM} = V_O = V^+/2$, $A_V = +1$ ($R_F = 0\Omega$), otherwise $R_F = 2 \ k\Omega$ for $A_V \neq +1$, $R_L = 1 \ k\Omega \parallel 5 \ pF$. **Boldface** Limits apply at temperature extremes.

Symbol	Parameter	Condition	Min (1)	Тур (2)	Max (1)	Units
Frequen	cy Domain Response					
SSBW	-3 dB Bandwidth Small Signal	$A_V = 1$, $R_L = 1$ k Ω , $V_{OUT} = 0.2$ V_{PP}		130		N 41 I
		$A_V = 2, -1, R_L = 1 \text{ k}\Omega, V_{OUT} = 0.2 V_{PP}$		53		MHZ
GBW	Gain Bandwidth (LMH6618)		54	64		MHz
GBW	Gain Bandwidth (LMH6619)		54	57		MHz
LSBW	-3 dB Bandwidth Large Signal	$A_V = 1$, $R_L = 1$ k Ω , $V_{OUT} = 2$ V_{PP}		15		N41 1-
		$A_V = 2, R_L = 150\Omega, V_{OUT} = 2 V_{PP}$		15		IVITIZ
Peak	Peaking	$A_V = 1, C_L = 5 \text{ pF}$		0.5		dB
0.1 dBBW	0.1 dB Bandwidth	$\begin{array}{l} A_{V}=2, \ V_{OUT}=0.5 \ V_{PP}, \\ R_{F}=R_{G}=1 \ k\Omega \end{array}$		15		MHz
DG	Differential Gain			0.1		%
DP	Differential Phase			0.1		deg
Time Do	main Response					
t _r /t _f	Rise & Fall Time	2V Step, A _V = 1		30		ns
SR	Slew Rate	2V Step, $A_V = 1$	44	55		V/µs
t _{s_0.1}	0.1% Settling Time	2V Step, A _V = −1		90		20
t _{s_0.01}	0.01% Settling Time	2V Step, $A_V = -1$		120		115
Distortio	on and Noise Performance					
SFDR	Spurious Free Dynamic Range	$f_{C} = 100 \text{ kHz}, V_{OUT} = 2 V_{PP}, R_{L} = 1 k\Omega$		100		
		$f_C = 1 \text{ MHz}, V_{OUT} = 2 V_{PP}, R_L = 1 k\Omega$		88		dBc
		$f_C = 5 \text{ MHz}, V_O = 2 V_{PP}, R_L = 1 \text{ k}\Omega$		61		
e _n	Input Voltage Noise Density	f = 100 kHz		10		nV//√Hz
i _n	Input Current Noise Density	f = 100 kHz		1		pA//√Hz
СТ	Crosstalk (LMH6619)	$f = 5 \text{ MHz}, \text{ V}_{IN} = 2 \text{ V}_{PP}$		80		dB
Input, DO	C Performance					
V _{OS}	Input Offset Voltage	$V_{CM} = 0.5V$ (pnp active) $V_{CM} = 4.5V$ (npn active)		0.1	±0.75 ±1.3	mV
TCV _{OS}	Input Offset Voltage Temperature Drift	(3)		0.8		μV/°C
I _B	Input Bias Current	$V_{CM} = 0.5V$ (pnp active)		-1.5	-2.4	
		$V_{CM} = 4.5V$ (npn active)		+1.0	+1.9	μΑ
I _{OS}	Input Offset Current			0.01	±0.26	μA
C _{IN}	Input Capacitance			1.5		pF
R _{IN}	Input Resistance			8		MΩ
CMVR	Common Mode Voltage Range	DC, CMRR ≥ 65 dB	-0.2		5.2	V
CMRR	Common Mode Rejection Ratio	ejection Ratio V _{CM} Stepped from -0.1V to 3.4V		98		dB
		V_{CM} Stepped from 4.0V to 5.1V	84	108		uВ
A _{OL}	Open Loop Voltage Gain	$R_L = 1 \ k\Omega$ to +4.6V or +0.4V	84	100		dR
		$R_L = 150\Omega$ to +4.5V or +0.5V	78	83		

(1) Limits are 100% production tested at 25°C. Limits over the operating temperature range are guaranteed through correlations using the Statistical Quality Control (SQC) method.

(2) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

(3) Voltage average drift is determined by dividing the change in V_{OS} by temperature change.

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+5V ELECTRICAL CHARACTERISTICS (continued)

Unless otherwise specified, all limits are guaranteed for $T_J = +25^{\circ}C$, $V^+ = 5V$, $V^- = 0V$, $\overline{\text{DISABLE}} = 5V$, $V_{CM} = V_O = V^+/2$, $A_V = +1$ ($R_F = 0\Omega$), otherwise $R_F = 2 k\Omega$ for $A_V \neq +1$, $R_L = 1 k\Omega \parallel 5 pF$. **Boldface** Limits apply at temperature extremes.

Symbol	Parameter	Condition	Min (1)	Тур (2)	Max (1)	Units
Output I	DC Characteristics					
V _{OUT}	Output Voltage Swing High (LMH6618) (Voltage from V ⁺ Supply Rail)	$R_L = 1 \ k\Omega$ to V ⁺ /2		60	73 82	
		$R_L = 150\Omega$ to V ⁺ /2		230	255 295	_
Output Voltage Swing Low (LMH6618) (Voltage from V ⁻ Supply Rail)	$R_L = 1 \ k\Omega$ to V ⁺ /2		75	83 96	mV from either rail	
	$R_L = 150\Omega$ to V ⁺ /2		250	270 321		
	$R_L = 150\Omega$ to V ⁻		32	43 45		
	Output Voltage Swing High (LMH6619) (Voltage from V ⁺ Supply Rail)	$R_L = 1 \ k\Omega$ to V ⁺ /2		60	73 82	
		$R_L = 150\Omega$ to V ⁺ /2		230	255 295	
Output Voltage Swing Low (LMH6619) (Voltage from V [−] Supply Rail)	$R_L = 1 \ k\Omega$ to V ⁺ /2		77	85 98	mV from either rail	
	$R_L = 150\Omega$ to V ⁺ /2		255	275 326		
		$R_L = 150\Omega$ to V ⁻		37	48 50	
I _{OUT}	Linear Output Current	$V_{OUT} = V^{+}/2^{(4)}$	±25	±35		mA
R _{OUT}	Output Resistance	f = 1 MHz		0.17		Ω
Enable I	Pin Operation		<u> </u>			
	Enable High Voltage Threshold	Enabled	3.0			V
	Enable Pin High Current	$V_{\overline{\text{DISABLE}}} = 5V$		1.2		μA
	Enable Low Voltage Threshold	Disabled			2.0	V
	Enable Pin Low Current	$V_{\overline{\text{DISABLE}}} = 0V$		2.5		μA
t _{on}	Turn-On Time			25		ns
t _{off}	Turn-Off Time			90		ns
Power S	Supply Performance	-			-j	-!
PSRR	Power Supply Rejection Ratio	DC, $V_{CM} = 0.5V$, $V_{S} = 2.7V$ to 11V	84	104		dB
I _S	Supply Current (LMH6618)	R _L = ∞		1.25	1.5 1.7	
	Supply Current (LMH6619) (per channel)	R _L = ∞		1.3	1.5 1.75	IIIA
I _{SD}	Disable Shutdown Current	DISABLE = 0V		72	105	μA

(4) Do not short circuit the output. Continuous source or sink currents larger than the I_{OUT} typical are not recommended as it may damage the part.

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±5V ELECTRICAL CHARACTERISTICS

Unless otherwise specified, all limits are guaranteed for $T_J = +25^{\circ}C$, $V^+ = 5V$, $V^- = -5V$, $\overline{\text{DISABLE}} = 5V$, $V_{CM} = V_O = 0V$, $A_V = +1$ ($R_F = 0\Omega$), otherwise $R_F = 2 \ k\Omega$ for $A_V \neq +1$, $R_L = 1 \ k\Omega \parallel 5 \ pF$. **Boldface** Limits apply at temperature extremes.

Symbol	Parameter	Condition	Min (1)	Тур (2)	Max (1)	Units
Frequen	cy Domain Response			1		
SSBW	-3 dB Bandwidth Small Signal	$A_V = 1, R_L = 1 \text{ k}\Omega, V_{OUT} = 0.2 V_{PP}$		140		
		$A_V = 2, -1, R_L = 1 \text{ k}\Omega, V_{OUT} = 0.2 V_{PP}$		53		MHZ
GBW	Gain Bandwidth (LMH6618)		54	65		MHz
GBW	Gain Bandwidth (LMH6619)		54	58		MHz
LSBW	-3 dB Bandwidth Large Signal	$A_V = 1$, $R_L = 1$ k Ω , $V_{OUT} = 2$ V_{PP}		16		
		$A_V = 2, R_L = 150\Omega, V_{OUT} = 2 V_{PP}$		15		MHZ
Peak	Peaking	$A_{V} = 1, C_{L} = 5 \text{ pF}$		0.05		dB
0.1 dBBW	0.1 dB Bandwidth			15		MHz
DG	Differential Gain	A_V = +2, 4.43 MHz, 0.6V < V _{OUT} < 2V, R _L = 150Ω to V ⁺ /2		0.1		%
DP	Differential Phase	A_V = +2, 4.43 MHz, 0.6V < V _{OUT} < 2V, R _L = 150Ω to V ⁺ /2		0.1		deg
Time Do	main Response		1	1		
t _r /t _f	Rise & Fall Time	2V Step, $A_V = 1$		30		ns
SR	Slew Rate	2V Step, A _V = 1	45	57		V/µs
t _{s_0.1}	0.1% Settling Time	2V Step, A _V = −1		90		
t _{s_0.01}	0.01% Settling Time	2V Step, A _V = −1		120		ns
Noise an	nd Distortion Performance	·				
SFDR	Spurious Free Dynamic Range	f_{C} = 100 kHz, V_{OUT} = 2 V_{PP} , R_{L} = 1 k Ω		100		
		f_{C} = 1 MHz, V_{OUT} = 2 V_{PP} , R_{L} = 1 $k\Omega$		88		dBc
		$f_{C} = 5 \text{ MHz}, V_{OUT} = 2 V_{PP}, R_{L} = 1 \text{ k}\Omega$		70		
en	Input Voltage Noise Density	f = 100 kHz		10		nV/√Hz
i _n	Input Current Noise Density	f = 100 kHz		1		pA/√Hz
СТ	Crosstalk (LMH6619)	$f = 5 \text{ MHz}, \text{ V}_{IN} = 2 \text{ V}_{PP}$		80		dB
Input DC	Performance					
V _{OS}	Input Offset Voltage	$V_{CM} = -4.5V$ (pnp active) $V_{CM} = 4.5V$ (npn active)		0.1	±0.75 ±1.3	mV
TCV _{OS}	Input Offset Voltage Temperature Drift	(3)		0.9		μV/°C
I _B	Input Bias Current	$V_{CM} = -4.5V$ (pnp active)		-1.5	-2.4	
		$V_{CM} = 4.5V$ (npn active)		+1.0	+1.9	μΑ
I _{OS}	Input Offset Current			0.01	±0.26	μA
C _{IN}	Input Capacitance			1.5		pF
R _{IN}	Input Resistance	8			MΩ	
CMVR	Common Mode Voltage Range	DC, CMRR ≥ 65 dB	-5.2		5.2	V
CMRR	Common Mode Rejection Ratio	V_{CM} Stepped from -5.1V to 3.4V	84	100		dB
		V_{CM} Stepped from 4.0V to 5.1V	83	108		uВ
A _{OL}	Open Loop Voltage Gain	R_L = 1 k Ω to +4.6V or -4.6V	86	95		dR
		$R_L = 150\Omega$ to +4.3V or -4.3V	79	84		

(1) Limits are 100% production tested at 25°C. Limits over the operating temperature range are guaranteed through correlations using the Statistical Quality Control (SQC) method.

(2) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

(3) Voltage average drift is determined by dividing the change in V_{OS} by temperature change.

TEXAS INSTRUMENTS

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±5V ELECTRICAL CHARACTERISTICS (continued)

Unless otherwise specified, all limits are guaranteed for $T_J = +25^{\circ}C$, $V^+ = 5V$, $V^- = -5V$, $\overline{\text{DISABLE}} = 5V$, $V_{CM} = V_0 = 0V$, $A_V = +1$ ($R_F = 0\Omega$), otherwise $R_F = 2 k\Omega$ for $A_V \neq +1$, $R_L = 1 k\Omega \parallel 5 pF$. **Boldface** Limits apply at temperature extremes.

Symbol	Parameter	Condition	Min (1)	Тур (2)	Max (1)	Units
Output D	DC Characteristics	·				
V _{OUT}	Output Voltage Swing High (LMH6618) (Voltage from V ⁺ Supply Rail)	$R_L = 1 \ k\Omega$ to GND		100	111 126	
		$R_L = 150\Omega$ to GND		430	457 526	_
	Output Voltage Swing Low (LMH6618) (Voltage from V [−] Supply Rail)	$R_L = 1 \ k\Omega$ to GND		110	121 136	mV from either rail
	$R_L = 150\Omega$ to GND		440	474 559		
		$R_L = 150\Omega$ to V ⁻		35	51 52	
	Output Voltage Swing High (LMH6619) (Voltage from V ⁺ Supply Rail)	$R_L = 1 \ k\Omega$ to GND		100	111 126	
		$R_L = 150\Omega$ to GND		430	457 526	
	Output Voltage Swing Low (LMH6619) (Voltage from V [−] Supply Rail)	$R_L = 1 \ k\Omega$ to GND		115	126 141	mV from either rail
		$R_L = 150\Omega$ to GND		450	484 569	
		$R_L = 150\Omega$ to V ⁻		45	61 62	
I _{OUT}	Linear Output Current	$V_{OUT} = V^{+}/2^{(4)}$	±25	±35		mA
R _{OUT}	Output Resistance	f = 1 MHz		0.17		Ω
Enable F	Pin Operation					
	Enable High Voltage Threshold	Enabled	0.5			V
	Enable Pin High Current	$V_{\overline{\text{DISABLE}}} = +5V$		16		μA
	Enable Low Voltage Threshold	Disabled			-0.5	V
	Enable Pin Low Current	$V_{\overline{\text{DISABLE}}} = -5V$		17		μA
t _{on}	Turn-On Time			25		ns
t _{off}	Turn-Off Time			90		ns
Power S	upply Performance					
PSRR	Power Supply Rejection Ratio	DC, V_{CM} = -4.5V, V_S = 2.7V to 11V	84	104		dB
I _S	Supply Current (LMH6618)	R _L = ∞		1.35	1.6 1.9	- m 4
	Supply Current (LMH6619) (per channel)	R _L = ∞		1.45	1.65 2.0	IIIA
I _{SD}	Disable Shutdown Current	DISABLE = -5V		103	140	μA

(4) Do not short circuit the output. Continuous source or sink currents larger than the I_{OUT} typical are not recommended as it may damage the part.

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Connection Diagram



Figure 1. 6-Pin SOT – Top View (See Package Number DDC0006A)



Figure 2. 8-Pin SOIC – Top View (See Package Number D0008A)



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TYPICAL PERFORMANCE CHARACTERISTICS

At $T_J = 25^{\circ}C$, $A_V = +1$ ($R_F = 0\Omega$), otherwise $R_F = 2 \text{ k}\Omega$ for $A_V \neq +1$, unless otherwise specified.

Closed Loop Frequency Response for Various Supplies

0 -3 ±1.5V -6 GAIN (dB) ±2.5V -9 -12 -15 Vout = 0.2V $R_L = 1 k\Omega$ -18 $C_L = 5 \, pF$ -21 10 100 1000 FREQUENCY (MHz) Figure 3.





Closed Loop Frequency Response for Various Temperatures





Closed Loop Frequency Response for Various Supplies



Closed Loop Frequency Response for Various Temperatures







TYPICAL PERFORMANCE CHARACTERISTICS (continued)

At $T_J = 25^{\circ}$ C, $A_V = +1$ ($R_F = 0\Omega$), otherwise $R_F = 2 k\Omega$ for $A_V \neq +1$, unless otherwise specified. **Closed Loop Gain vs. Frequency for Various Gains Large Signal Frequency Respon**



Figure 9.











Small Signal Frequency Response with Various Capacitive Load



Figure 12.







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TYPICAL PERFORMANCE CHARACTERISTICS (continued)

Figure 49.

Crosstalk Rejection vs. Frequency (Output to Output)

Figure 50.

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APPLICATION INFORMATION

The LMH6618 and LMH6619 are based on TI's proprietary VIP10 dielectrically isolated bipolar process. This device family architecture features the following:

- Complimentary bipolar devices with exceptionally high f_t (~8 GHz) even under low supply voltage (2.7V) and low bias current.
- Common emitter push-push output stage. This architecture allows the output to reach within millivolts of either supply rail.
- Consistent performance from any supply voltage (2.7V 11V) with little variation with supply voltage for the most important specifications (e.g. BW, SR, I_{OUT}.)
- Significant power saving compared to competitive devices on the market with similar performance.

With 3V supplies and a common mode input voltage range that extends beyond either supply rail, the LMH6618 and LMH6619 are well suited to many low voltage/low power applications. Even with 3V supplies, the -3 dB BW (at A_V = +1) is typically 120 MHz.

The LMH6618 and LMH6619 are designed to avoid output phase reversal. With input over-drive, the output is kept near the supply rail (or as close to it as mandated by the closed loop gain setting and the input voltage). Figure 62 shows the input and output voltage when the input voltage significantly exceeds the supply voltages.

Figure 62. Input and Output Shown with CMVR Exceeded

If the input voltage range is exceeded by more than a diode drop beyond either rail, the internal ESD protection diodes will start to conduct. The current flow in these ESD diodes should be externally limited.

The LMH6618 can be shutdown by connecting the DISABLE pin to <u>a voltage</u> 0.5V below the supply midpoint which will reduce the supply current to typically less than 100 μ A. The DISABLE pin is "active low" and should be connected through a resistor to V⁺ for normal operation. Shutdown is guaranteed when the DISABLE pin is 0.5V below the supply midpoint at any operating supply voltage and temperature.

In the shutdown mode, essentially all internal device biasing is turned off in order to minimize supply current flow and the output goes into high impedance mode. During shutdown, the input stage has an equivalent circuit as shown in Figure 63.

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When the LMH6618 is shutdown, there may be current flow through the internal diodes shown, caused by input potential, if present. This current may flow through the external feedback resistor and result in an apparent output signal. In most shutdown applications the presence of this output is inconsequential. However, if the output is "forced" by another device, the other device will need to conduct the current described in order to maintain the output potential.

To keep the output at or near ground during shutdown when there is no other device to hold the output low, a switch using a transistor can be used to shunt the output to ground.

SINGLE CHANNEL ADC DRIVER

The low noise and wide bandwidth make the LMH6618 an excellent choice for driving a 12-bit ADC. Figure 64 shows the schematic of the LMH6618 driving an ADC121S101. The ADC121S101 is a single channel 12-bit ADC. The LMH6618 is set up in a 2nd order multiple-feedback configuration with a gain of -1. The -3 dB point is at 500 kHz and the -0.01 dB point is at 100 kHz. The 22 Ω resistor and 390 pF capacitor form an antialiasing filter for the ADC121S101. The capacitor also stores and delivers charge to the switched capacitor input of the ADC. The capacitive load on the LMH6618 created by the 390 pF capacitor is decreased by the 22 Ω resistor. Table 1 shows the performance data of the LMH6618 and the ADC121S101.

Figure 64. LMH6618 Driving an ADC121S101

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······································				
Parameter	Measured Value			
Signal Frequency	100 kHz			
Signal Amplitude	4.5V			
SINAD	71.5 dB			
SNR	71.87 dB			
THD	-82.4 dB			
SFDR	90.97 dB			
ENOB	11.6 bits			

Table 1. Performance Data for the LMH6618 Driving an ADC121S101

When the op amp and the ADC are using the same supply, it is important that both devices are well bypassed. A 0.1 μ F ceramic capacitor and a 10 μ F tantalum capacitor should be located as close as possible to each supply pin. A sample layout is shown in Figure 65. The 0.1 μ F capacitors (C13 and C6) and the 10 μ F capacitors (C11 and C5) are located very close to the supply pins of the LMH6618 and the ADC121S101.

Figure 65. LMH6618 and ADC121S101 Layout

SINGLE TO DIFFERENTIAL ADC DRIVER

Figure 66 shows the LMH6619 used to drive a differential ADC with a single-ended input. The ADC121S625 is a fully differential 12-bit ADC. Table 2 shows the performance data of the LMH6619 and the ADC121S625.

Figure 66. LMH6619 Driving an ADC121S625

Tahlo 2	Performance	Data for th	ho I MH6619	Driving an	ADC121S625
i able z.	renormance			Driving an	ADG1213023

Parameter	Measured Value
Signal Frequency	10 kHz
Signal Amplitude	2.5V
SINAD	67.9 dB
SNR	68.29 dB
THD	-78.6 dB
SFDR	75.0 dB
ENOB	11.0 bits

DIFFERENTIAL ADC DRIVER

The circuit in Figure 64 can be used to drive both inputs of a differential ADC. Figure 67 shows the LMH6619 driving an ADC121S705. The ADC121S705 is a fully differential 12-bit ADC. Performance with this circuit is similar to the circuit in Figure 64.

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Figure 67. LMH6619 Driving an ADC121S705

DC LEVEL SHIFTING

Often a signal must be both amplified and level shifted while using a single supply for the op amp. The circuit in Figure 68 can do both of these tasks. The procedure for specifying the resistor values is as follows.

- 1. Determine the input voltage.
- 2. Calculate the input voltage midpoint, $V_{INMID} = V_{INMIN} + (V_{INMAX} V_{INMIN})/2$.
- 3. Determine the output voltage needed.
- 4. Calculate the output voltage midpoint, $V_{OUTMID} = V_{OUTMIN} + (V_{OUTMAX} V_{OUTMIN})/2$.
- 5. Calculate the gain needed, gain = $(V_{OUTMAX} V_{OUTMIN})/(V_{INMAX} V_{INMIN})$
- 6. Calculate the amount the voltage needs to be shifted from input to output, $\Delta V_{OUT} = V_{OUTMID} \text{gain x } V_{INMID}$.
- 7. Set the supply voltage to be used.
- 8. Calculate the noise gain, noise gain = gain + $\Delta V_{OUT}/V_S$.
- 9. Set R_F.
- 10. Calculate R_1 , $R_1 = R_F$ /gain.
- 11. Calculate R_2 , $R_2 = R_F/(noise gain-gain)$.
- 12. Calculate R_G , $R_G = R_F/(noise gain 1)$.

Check that both the V_{IN} and V_{OUT} are within the voltage ranges of the LMH6618.

The following example is for a V_{IN} of 0V to 1V with a V_{OUT} of 2V to 4V.

- 1. $V_{IN} = 0V$ to 1V
- 2. $V_{INMID} = 0V + (1V 0V)/2 = 0.5V$
- 3. $V_{OUT} = 2V$ to 4V

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LMH6618, LMH6619

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- 4. $V_{OUTMID} = 2V + (4V 2V)/2 = 3V$
- 5. Gain = (4V 2V)/(1V 0V) = 2
- 6. $\Delta V_{OUT} = 3V 2 \times 0.5V = 2$
- 7. For the example the supply voltage will be +5V.
- 8. Noise gain = 2 + 2/5V = 2.4
- 9. $R_F = 2 k\Omega$
- 10. $R_1 = 2 k\Omega/2 = 1 k\Omega$
- 11. $R_2 = 2 k\Omega/(2.4-2) = 5 k\Omega$
- 12. $R_G = 2 k\Omega/(2.4 1) = 1.43 k\Omega$

4th ORDER MULTIPLE FEEDBACK LOW-PASS FILTER

Figure 69 shows the LMH6619 used as the amplifier in a multiple feedback low pass filter. This filter is set up to have a gain of +1 and a -3 dB point of 1 MHz. Values can be determined by using the WEBENCH[®] Active Filter Designer found at webench.ti.com.

Figure 69. 4th Order Multiple Feedback Low-Pass Filter

CURRENT SENSE AMPLIFIER

With it's rail-to-rail input and output capability, low V_{OS}, and low I_B the LMH6618 is an ideal choice for a current sense amplifier application. Figure 70 shows the schematic of the LMH6618 set up in a low-side sense configuration which provides a conversion gain of 2V/A. Voltage error due to V_{OS} can be calculated to be V_{OS} x (1 + R_F/R_G) or 0.75 mV x 20.6 = 15.5 mV. Voltage error due to I_O is I_O x R_F or 0.26 μ A x 1 k Ω = 0.26 mV. Hence total voltage error is 15.5 mV + 0.26 mV or 15.7 mV which translates into a current error of 15.7 mV/(2 V/A) = 7.9 mA.

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Figure 70. Current Sense Amplifier

TRANSIMPEDANCE AMPLIFIER

By definition, a photodiode produces either a current or voltage output from exposure to a light source. A Transimpedance Amplifier (TIA) is utilized to convert this low-level current to a usable voltage signal. The TIA often will need to be compensated to insure proper operation.

Figure 71. Photodiode Modeled with Capacitance Elements

Figure 71 shows the LMH6618 modeled with photodiode and the internal op amp capacitances. The LMH6618 allows circuit operation of a low intensity light due to its low input bias current by using larger values of gain (R_F). The total capacitance (C_T) on the inverting terminal of the op amp includes the photodiode capacitance (C_{PD}) and the input capacitance of the op amp (C_{IN}). This total capacitance (C_T) plays an important role in the stability of the circuit. The noise gain of this circuit determines the stability and is defined by:

$$NG = \frac{1 + SR_F (C_T + C_F)}{1 + SC_F R_F}$$
(1)
Where, $f_Z \cong \frac{1}{2\pi R_F C_T}$ and $f_P = \frac{1}{2\pi R_F C_F}$
(2)

(2)

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Figure 72. Bode Plot of Noise Gain Intersecting with Op Amp Open-Loop Gain

Figure 72 shows the bode plot of the noise gain intersecting the op amp open loop gain. With larger values of gain, C_T and R_F create a zero in the transfer function. At higher frequencies the circuit can become unstable due to excess phase shift around the loop.

A pole at f_P in the noise gain function is created by placing a feedback capacitor (C_F) across R_F . The noise gain slope is flattened by choosing an appropriate value of C_F for optimum performance.

Theoretical expressions for calculating the optimum value of $C_{\rm F}$ and the expected -3 dB bandwidth are:

$$C_{\rm F} = \sqrt{\frac{C_{\rm T}}{2\pi R_{\rm F} (\rm GBWP)}}$$
(3)
$$f_{-3\,\rm dB} = \sqrt{\frac{\rm GBWP}{2\pi R_{\rm F} C_{\rm T}}}$$
(4)

Equation 4 indicates that the -3 dB bandwidth of the TIA is inversely proportional to the feedback resistor. Therefore, if the bandwidth is important then the best approach would be to have a moderate transimpedance gain stage followed by a broadband voltage gain stage.

Table 3 shows the measurement results of the LMH6618 with different photodiodes having various capacitances (C_{PD}) and a feedback resistance (R_F) of 1 k Ω .

		,	•			
C _{PD}	CT	C _{F CAL}	C _{F USED}	f _{-3 dB CAL}	f –3 dB MEAS	Peaking
(pF)	(pF)	(pF)	(pF)	(MHz)	(MHz)	(dB)
22	24	7.7	5.6	23.7	20	0.9
47	49	10.9	10	16.6	15.2	0.8
100	102	15.8	15	11.5	10.8	0.9
222	224	23.4	18	7.81	8	2.9

Table 3. TIA (Figure 1) Compensation and Performance Results

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Figure 73 shows the frequency response for the various photodiodes in Table 3.

Figure 73. Frequency Response for Various Photodiode and Feedback Capacitors

When analyzing the noise at the output of the TIA, it is important to note that the various noise sources (i.e. op amp noise voltage, feedback resistor thermal noise, input noise current, photodiode noise current) do not all operate over the same frequency band. Therefore, when the noise at the output is calculated, this should be taken into account. The op amp noise voltage will be gained up in the region between the noise gain's zero and pole (f_Z and f_P in Figure 72). The higher the values of R_F and C_T , the sooner the noise gain peaking starts and therefore its contribution to the total output noise will be larger. It is obvious to note that it is advantageous to minimize C_{IN} by proper choice of op amp or by applying a reverse bias across the diode at the expense of excess dark current and noise.

DIFFERENTIAL CABLE DRIVER FOR NTSC VIDEO

The LMH6618 and LMH6619 can be used to drive an NTSC video signal on a twisted-pair cable. Figure 74 shows the schematic of a differential cable driver for NTSC video. This circuit can be used to transmit the signal from a camera over a twisted pair to a monitor or display located a distance. C_1 and C_2 are used to AC couple the video signal into the LMH6619. The two amplifiers of the LMH6619 are set to a gain of 2 to compensate for the 75 Ω back termination resistors on the outputs. The LMH6618 is set to a gain of 1. Because of the DC bias the output of the LMH6618 is AC coupled. Most monitors and displays will accept AC coupled inputs.

PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Top-Side Markings	Samples
	(1)		Drawing		Qty	(2)		(3)		(4)	
LMH6618MK/NOPB	ACTIVE	SOT	DDC	6	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	AE4A	Samples
LMH6618MKE/NOPB	ACTIVE	SOT	DDC	6	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	AE4A	Samples
LMH6618MKX/NOPB	ACTIVE	SOT	DDC	6	3000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	AE4A	Samples
LMH6619MA/NOPB	ACTIVE	SOIC	D	8	95	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMH66 19MA	Samples
LMH6619MAE/NOPB	ACTIVE	SOIC	D	8	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMH66 19MA	Samples
LMH6619MAX/NOPB	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMH66 19MA	Samples

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

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Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) Multiple Top-Side Markings will be inside parentheses. Only one Top-Side Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Top-Side Marking for that device.

11-Apr-2013

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OTHER QUALIFIED VERSIONS OF LMH6619 :

• Automotive: LMH6619-Q1

NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

*All dimensions are nominal												
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH6618MK/NOPB	SOT	DDC	6	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6618MKE/NOPB	SOT	DDC	6	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6618MKX/NOPB	SOT	DDC	6	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6619MAE/NOPB	SOIC	D	8	250	178.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1
LMH6619MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1

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PACKAGE MATERIALS INFORMATION

21-Mar-2013

*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMH6618MK/NOPB	SOT	DDC	6	1000	210.0	185.0	35.0
LMH6618MKE/NOPB	SOT	DDC	6	250	210.0	185.0	35.0
LMH6618MKX/NOPB	SOT	DDC	6	3000	210.0	185.0	35.0
LMH6619MAE/NOPB	SOIC	D	8	250	210.0	185.0	35.0
LMH6619MAX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0

DDC (R-PDSO-G6)

PLASTIC SMALL-OUTLINE

Α. All linear dimensions are in millimeters.

- This drawing is subject to change without notice. Β.
- C. Body dimensions do not include mold flash or protrusion.
- D. Falls within JEDEC MO-193 variation AA (6 pin).

NOTES:

A. All linear dimensions are in millimeters.B. This drawing is subject to change without notice.

C. Publication IPC-7351 is recommended for alternate designs.

D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.

D (R-PDSO-G8)

PLASTIC SMALL OUTLINE

NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.

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